

# Introduction to Particle-in-cell gyrokinetic simulations

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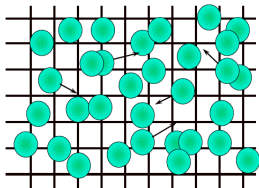
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# The traditional PIC method in plasma physics

Method to simulate collective phenomena in plasmas:

- Plasma is described by a small number of **super-particles (SP)**, each SP represents many ions or electrons, each SP describes a piece of the distribution function  $f$ .
- The motion of the SPs is straightforwardly described by the Newton-Maxwell equations.
- The self-consistent fields are calculated by projecting on a **spatial grid** charge and current associated with each SP.



# The PIC method in general..

The PIC method is a **numerical technique** used to solve a certain class of partial differential equations:

- individual particles (or fluid elements) in a Lagrangian frame are tracked in continuous phase space
- moments of the distribution function are computed simultaneously on Eulerian (stationary) mesh points.

Solid and fluid mechanics, cosmology,...

Plasma physics:

laser-plasma interactions, electron acceleration and ion heating in the auroral ionosphere, magnetic reconnection...**Gyrokinetics**

# Outline

- **Construct a set of gyrokinetic (GK) equations**, suited for simulations:
  - 1) Must **preserve symmetries**: conserved quantities (energy).
  - 2) Must contain (only) relevant physics: **approximation** are needed, but **must not break self-consistency**.

General procedure: **GK field theory**.

Example: Electrostatic, linearised polarisation GK Vlasov-Maxwell.

- **PIC discretization** for particle and field eqs. (finite elements).
- **Properties** of the discretised equations (conservation, errors, convergences,..).
- Examples, simulations of experimental plasmas.

# Self-consistent gyrokinetic equation from GK Lagrangian

**GOAL:** construct a simple self-consistent, energy conserving set of gyrokinetic equations, suited for PIC discretisation:

**Electrostatic, linearised polarisation GK Vlasov-Maxwell system.**

- **Not only an academic problem:** state of the art up  $\sim$  5 years ago, still useful for many physics problems.
- Traditionally, iterative method [Friemann & Chen 1979...] or Hamiltonian representation to get Vlasov equation from particle Lagrangian; a back transformation (Lie) was used to obtain the field equations [Hahm 1988...].

# Self-consistent gyrokinetic equation from GK Lagrangian

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**TOOL:** gyrokinetic field theory.

# Self-consistent gyrokinetic equation from GK Lagrangian

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Electrostatic, linearised polarisation GK Vlasov-Maxwell system

**TOOL:** gyrokinetic field theory.

- 1) Establish a proper GK Lagrangian for particles and fields.
- 2) Approximate the Lagrangian.
- 3) Classical field theory: derive equations for particles and fields from variational principles.

The symmetry and conservation properties are preserved.



## Particle Lagrangian with time dependence in Hamiltonian

**STARTING POINT:** Lie transformed low-frequency particle Lagrangian in gyrocenter coordinates

$$L_p \equiv \left( \frac{e}{c} \mathbf{A} + p_{\parallel} \mathbf{b} \right) \cdot \dot{\mathbf{R}} + \frac{mc}{e} \mu \dot{\theta} - H$$

$\mathbf{R}$ , gyrocenter positions;  $\mu \equiv \frac{mv_{\perp}^2}{2B}$ , magnetic moment;  
 $p_{\parallel} \equiv mU - \frac{e}{c} J_0 A_{\parallel}$ , canonical parallel momentum;  $\theta$ , gyroangle;  
 $\mathbf{B} = \nabla \times \mathbf{A}$ , background (static) magnetic field;  $J_0$  gyroaverage operator,  $U$  parallel velocity.

Lie transform method is rather general: choices can be made to arrange  $L_p$  so that the symplectic part depends only on the background, while all the **time varying fields are contained in the Hamiltonian  $H$** .

[Hahm 1988, Brizard 2007, Miyato 2009,...].





## GK total Lagrangian contains all the needed physics

Following [Sugama 2000], Lagrangian for **particles** AND **fields** is:

$$L = \sum_{\text{sp}} \int dW_0 dV f(\mathbf{Z}_0, t_0) L_p(\mathbf{Z}(\mathbf{Z}_0, t_0; t), \dot{\mathbf{Z}}(\mathbf{Z}_0, t_0; t), t) \\ + \int dV \frac{E^2 - B_{\perp}^2}{8\pi}$$

$$\mathbf{Z} \equiv (\mathbf{R}, p_{\parallel}, \mu, \theta); dW \equiv \frac{2\pi}{m^2} B_{\parallel}^* dp_{\parallel} d\mu; B_{\perp}^2 = |\nabla_{\perp} A_{\parallel}|^2$$

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The first term is the Lagrangian for charged particles.

- $f(\mathbf{Z}_0)$  is the distribution function for the species  $sp$  at an arbitrary initial time  $t_0$ .
- $L_p$  is the Lie transformed particle Lagrangian written in terms of the gyro-center coordinates, *Lagrangian density*.

## GK total Lagrangian contains all the needed physics

Following [Sugama 2000], the GK total Lagrangian is:

$$L = \sum_{\text{sp}} \int dW_0 dV f(\mathbf{Z}_0, t_0) L_p(\mathbf{Z}(\mathbf{Z}_0, t_0; t), \dot{\mathbf{Z}}(\mathbf{Z}_0, t_0; t), t) \\ + \int dV \frac{E^2 - B_{\perp}^2}{8\pi}$$

The second term is the Lagrangian for the electromagnetic fields.

Note: the particle Hamiltonian is not an invariant in GK theory.  
The conserved quantity is the total energy of the system.

## Total Lagrangian contains the Vlasov equation

- Particle number conservation condition:

$$dW_0 dV f(\mathbf{Z}_0, t_0) = dW dV f(\mathbf{Z}, t)$$

- The time dependence in the distribution function  $f(\mathbf{Z}, t)$  is:

$$\frac{2\pi}{m^2} B_{\parallel}^* f(\mathbf{Z}, t) = \int dW_0 dV f(\mathbf{Z}_0, t_0) \delta(\mathbf{Z} - \mathbf{Z}_0)$$

- Taking the time derivative of this equation, with some algebra, the **GK Vlasov equation** can be obtained:

$$\frac{\partial}{\partial t} f(\mathbf{Z}, t) + \frac{d\mathbf{Z}}{dt} \cdot \frac{\partial}{\partial \mathbf{Z}} f(\mathbf{Z}, t) = 0$$

Full derivation, for example: [Miyato 2009].

## Total Lagrangian: summary

$$L = \sum_{\text{sp}} \int dW dV f(\mathbf{z}, t) L_p + \int dV \frac{E^2 - B_{\perp}^2}{8\pi}$$
$$L_p = \left( \frac{e}{c} \mathbf{A} + p_{\parallel} \mathbf{b} \right) \cdot \dot{\mathbf{R}} + \frac{mc}{e} \mu \dot{\theta} - H$$
$$H = H(\Phi, A_{\parallel})$$

- Contains the Vlasov equation.
- Only one assumption on the Hamiltonian: it must contain the electrostatic potentials  $\Phi$  and the parallel component of the fluctuation magnetic potential  $A_{\parallel}$ .

## Total Lagrangian with simplest Hamiltonian [Hahm 1988]

$$L = \sum_{\text{sp}} \int dW dV f(\mathbf{z}, t) L_p + \int dV \frac{E^2 - B_{\perp}^2}{8\pi}$$
$$L_p = \left( \frac{e}{c} \mathbf{A} + p_{\parallel} \mathbf{b} \right) \cdot \dot{\mathbf{R}} + \frac{mc}{e} \mu \dot{\theta} - H$$
$$H = m \frac{U^2}{2} + \mu B + e J_0 \Phi - \frac{mc^2}{2B^2} |\nabla_{\perp} \Phi|^2$$

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$$H = m \frac{U^2}{2} + \mu B + e J_0 \Phi - \frac{mc^2}{2B^2} |\nabla_{\perp} \Phi|^2$$

- H is second order in the fields ( $p_{\parallel} \equiv mU - \frac{e}{c} J_0 A_{\parallel}$ )...

$$H = H_0 + H_1 + H_2$$

$$H_0 \equiv \frac{p_{\parallel}^2}{2m} + \mu B$$

$$H_1 \equiv e(J_0 \Phi - \frac{p_{\parallel}}{mc} J_0 A_{\parallel}) \equiv e J_0 \Psi$$

$$H_2 \equiv \frac{e^2}{2mc^2} (J_0 A_{\parallel})^2 - \frac{mc^2}{2B^2} |\nabla_{\perp} \Phi|^2$$

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- This is all we need from GK... from now on, field theory.
- In the context of **field theory**, this Lagrangian can be further approximated, without losing self-consistency and energetic consistency of the final equations.
- **Simmetry property of the Lagrangian will be automatically transferred to the equations.**



## Quasi-neutrality approximation

$$L = \sum_{\text{sp}} \int dW dV f(\mathbf{z}, t) L_p + \int dV \left( \frac{E^2}{8\pi} - \frac{B_{\perp}^2}{8\pi} \right)$$

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$$\int dV \frac{E^2}{8\pi} + \int dW dV f \frac{m}{2} \frac{c^2}{B^2} |\nabla_{\perp} \Phi|^2 = \frac{1}{8\pi} \int dV \left( 1 + \frac{\rho_S^2}{\lambda_d^2} \right) |\nabla_{\perp} \Phi|^2$$

$\lambda_d^2 \equiv \frac{k_B T_e}{4\pi n e^2}$  Debye length;  $\rho_S^2 \equiv \frac{k_B T_e m c^2}{e^2 B^2}$  ion sound Larmor radius.

$$\text{Fusion plasmas : } \frac{\rho_S^2}{\lambda_d^2} = \frac{4\pi n m c^2}{B^2} = \frac{c^2}{v_a^2} \gg 1$$

where  $v_a$  is the Alfvén velocity,  $c$  speed of light.



## Quasi-neutrality approximation

$$L = \sum_{\text{sp}} \int dW dV f(\mathbf{z}, t) L_p + \int dV \left( \frac{E^2}{8\pi} - \frac{B_{\perp}^2}{8\pi} \right)$$

$$L_p = \left( \frac{e}{c} \mathbf{A} + p_{\parallel} \mathbf{b} \right) \cdot \dot{\mathbf{R}} + \frac{mc}{e} \mu \dot{\theta} - H$$

$$H = \frac{p_{\parallel}^2}{2m} + \mu B + e(J_0 \Phi - \frac{p_{\parallel}}{mc} J_0 A_{\parallel}) + \frac{e^2}{2mc^2} (J_0 A_{\parallel})^2 - \frac{mc^2}{2B^2} |\nabla_{\perp} \Phi|^2$$

## Linearised polarisation approximation

$$L = \sum_{\text{sp}} \int dV dW \left( \left( \frac{e}{c} \mathbf{A} + p_{\parallel} \mathbf{b} \right) \cdot \dot{\mathbf{R}} + \frac{mc}{e} \mu \dot{\theta} - H \right) f - \int dV \frac{B_{\perp}^2}{8\pi}$$

- Start from  $H = H_0 + H_1 + H_2$
- In the Lagrangian  $H_0 + H_1$  only multiplies  $f$ :  $(H_0 + H_1)f$
- For  $H_2$ ,  $f$  is replaced by an equilibrium distribution function  $f_M$  independent of time:  $H_2 f_M$

$$L = \sum_{\text{sp}} \int dV dW \left( \left( \frac{e}{c} \mathbf{A} + p_{\parallel} \mathbf{b} \right) \cdot \dot{\mathbf{R}} + \frac{mc}{e} \mu \dot{\theta} - H_0 - H_1 \right) f \\ + \sum_{\text{sp}} \int dV dW H_2 f_M - \int dV \frac{B_{\perp}^2}{8\pi}$$

This approximation will lead to linearised field equations.

## Electrostatic model

- Although electromagnetic effects are important to correctly describe experimental plasmas, in the following we will neglect magnetic perturbations,  $A_{\parallel} = 0$  and  $p_{\parallel} = mU$ .

$$L = \sum_{\text{sp}} \int dV dW \left( \left( \frac{e}{c} \mathbf{A} + p_{\parallel} \mathbf{b} \right) \cdot \dot{\mathbf{R}} + \frac{mc}{e} \mu \dot{\theta} - H_0 - H_1 \right) f \\ + \sum_{\text{sp}} \int dV dW \frac{mc^2}{2B^2} |\nabla_{\perp} \Phi|^2$$

- From now on, **any additional approximation** or ordering will **break the symmetry** and conservation properties of the underlying dynamical system.

## Euler-Lagrange equations

- From the GK Lagrangian using variational principles for the **action functional**  $I$ , functional derivatives [Morrison 2005]:

$$\delta I = \int_{t_1}^{t_2} \delta L dt$$

- Euler-Lagrange equations, **functional derivatives** with respect to the particle phase space positions  $\mathbf{Z} = (\mathbf{R}, p_{\parallel}, \mu)$ :

$$\frac{\delta I}{\delta \mathbf{Z}} = 0 \Rightarrow \frac{\delta L}{\delta \mathbf{Z}} = 0$$

as  $t_1$  and  $t_2$  are arbitrary.

## Euler-Lagrange equations, electrostatic H

- With the simple Lagrangian:

$$\dot{\mathbf{R}} = \frac{\partial(H_0 + H_1)}{\partial p_{\parallel}} \frac{\mathbf{B}^*}{B_{\parallel}^*} - \frac{c}{eBB_{\parallel}^*} \mathbf{F} \cdot \nabla(H_0 + H_1)$$
$$\dot{p}_{\parallel} = -\frac{\mathbf{B}^*}{B_{\parallel}^*} \cdot \nabla(H_0 + H_1)$$

where a drift **tensor notation** for the background magnetic field has been used, in which  $\epsilon$  is the rank-three Levi-Civita pseudotensor:

$$\mathbf{F} = \nabla \mathbf{A} - (\nabla \mathbf{A})^T, \quad \mathbf{F} = \epsilon \cdot \mathbf{B}, \quad \nabla \times \mathbf{b} = -\nabla \cdot \frac{\mathbf{F}}{B}, \quad \mathbf{b} \times \mathbf{C} = -\frac{\mathbf{F}}{B} \cdot \mathbf{C} \quad \forall \mathbf{C}$$

$$\mathbf{A}^* = \mathbf{A} + p_{\parallel} \frac{c}{e} \mathbf{b}, \quad \mathbf{B}^* = \nabla \times \mathbf{A}^*$$

## Euler-Lagrange equations, no tensors

- Same equations in a more familiar form:

$$\begin{aligned}\dot{\mathbf{R}} &= \frac{p_{\parallel}}{m} \mathbf{b} - \left(\frac{p_{\parallel}}{m}\right)^2 \frac{mc}{eB_{\parallel}^*} \mathbf{b} \times \frac{\nabla p}{B^2} \\ &+ \left(\frac{\mu B}{m} + \left(\frac{p_{\parallel}}{m}\right)^2\right) \frac{mc}{eB_{\parallel}^*} \mathbf{b} \times \frac{\nabla B}{B} + \frac{c}{eB_{\parallel}^*} e\mathbf{b} \times \nabla J_0 \Phi,\end{aligned}$$

$$\begin{aligned}\dot{p}_{\parallel} &= \mu B \nabla \cdot \mathbf{b} + \frac{\mu c}{eB_{\parallel}^*} p_{\parallel} \mathbf{b} \times \frac{\nabla p}{B^2} \cdot \nabla B \\ &+ e \nabla J_0 \Phi \cdot \left( -\mathbf{b} + \frac{c}{eB_{\parallel}^*} p_{\parallel} \left( \mathbf{b} \times \frac{\nabla p}{B^2} - \frac{\mathbf{b} \times \nabla B}{B} \right) \right)\end{aligned}$$

$$\nabla p \equiv \frac{1}{4\pi} (\nabla \times \mathbf{B} \times \mathbf{B})$$



## Tensor formalism emphasizes symmetries

- The previous equation can be cast in the form of an **antisymmetric generalised bracket** [Scott 2010]:

$$B_{\parallel}^* \frac{\partial f}{\partial t} + \nabla H \cdot \frac{\partial \mathbf{G}}{\partial p_{\parallel}} \cdot \nabla f + (-\nabla \cdot \mathbf{G}) \cdot \left( \frac{\partial H}{\partial p_{\parallel}} \nabla f - \frac{\partial f}{\partial p_{\parallel}} \nabla H \right) = 0$$

having defined  $\mathbf{G} \equiv \epsilon \cdot \mathbf{A}^*$ .

- This structure has the form of a triple bracket:

$$[H, G^{ab}, f]_{azb} = \frac{\partial G^{ab}}{\partial p_{\parallel}} [H, f]_{ab} + (\nabla_a G^{ab}) [H, f]_{bz} + (\nabla_b G^{ab}) [H, f]_{za}$$

$ab$  are pairs of spatial indices,  $z$  denotes the  $p_{\parallel}$  coordinate.

- The two-bracket form is

$$[H, f]_{ab} = H_{,a} f_{,b} - H_{,b} f_{,a}$$

$g_{,a}$  denotes differentiation with respect to variable with index  $a$ .

## Vlasov equation has a symmetric form

- $\mathbf{A}^*$  has no  $p_{\parallel}$  component:  
additional fictitious 3-brackets can be added, leading to a remarkably symmetric expression for the gyrokinetic Vlasov equation.

$$\frac{\partial f}{\partial t} + \frac{1}{\sqrt{g}B_{\parallel}^*} \epsilon^{abcz} H_{,a} f_{,b} A_{c,z}^* = 0$$

where Einstein summation convention is assumed.

$\epsilon^{abcz}$  is the antisymmetric rank-four Levi-Civita pseudotensor.

- The antisymmetric bracket form of the GK Vlasov equations allows for **straightforward conservation** of several quantities, including particle number and energy.

## Field equation: Polarisation equation

- Functional derivative of  $L$  with respect to  $\Phi$ :

$$\frac{\delta L}{\delta \Phi} = 0 \rightarrow \frac{\delta fH}{\delta \Phi} = 0$$

which implies, with some algebra,

$$\sum_{\text{sp}} \int dV \delta \Phi \int dW \left( eJ_0 f + \frac{1}{B_{\parallel}^*} \nabla (B_{\parallel}^* \frac{mc^2}{B^2} f_M \nabla_{\perp} \Phi) \right) = 0$$

the  $J_0$  operator must be Hermitian.

- The arbitrariness of  $\delta \Phi$  implies:

$$\sum_{\text{sp}} \int dW \left( eJ_0 f + \frac{1}{B_{\parallel}^*} \nabla \left( \frac{mc^2}{B^2} B_{\parallel}^* f_M \nabla_{\perp} \Phi \right) \right) = 0$$

## Field equation: Polarisation equation

- $dp_{\parallel}d\mu$  commutes with  $\nabla$ :

$$\sum_{sp} \left( \int dW e J_0 f + \nabla \frac{n_0 mc^2}{B^2} \nabla_{\perp} \frac{mc^2}{B^2} \Phi \right) = 0$$

$n_0$  is the density associated with the equilibrium Maxwellian  $f_M$ .

- The polarization equation clarifies the approximations made:
  - 1) It is a **linear** equation.
  - 2) It has the form of  $\sum_{sp} en_{sp} = 0$ , where  $en_{sp}$  is the *particle density*, i.e. a quasi-neutrality condition.

## Global energy conservation equation

$$\frac{\partial f}{\partial t} + \frac{1}{\sqrt{g}B_{\parallel}^*} \epsilon^{abcz} H_{,a} f_{,b} A_{c,z}^* = 0$$

- Multiply by  $H$ , use linearity of the derivatives in the brackets and symmetry:

$$\frac{\partial fH}{\partial t} + \frac{1}{\sqrt{g}B_{\parallel}^*} \epsilon^{abcz} H_{,a} (fH)_{,b} A_{c,z}^* = f \frac{\partial H}{\partial t}$$

- Integrate over phase-space, sum over species:

$$\sum_{\text{sp}} \int dW dV \frac{\partial fH}{\partial t} = \sum_{\text{sp}} \int dW dV f \frac{\partial H}{\partial t}$$

- functional derivatives:

$$\sum_{\text{sp}} \int dW dV \frac{\partial fH}{\partial t} = \int dV \sum_{\text{sp}} \frac{\delta fH}{\delta \Phi} \frac{\partial \Phi}{\partial t} = 0$$

## Global energy conservation equation

- Finally:

$$\frac{\partial}{\partial t} \mathcal{E} \equiv \frac{\partial}{\partial t} \sum_{\text{sp}} \int dV dW f H = 0$$

- The Hamiltonian is the global energy.
- Not true for electromagnetic (EM) Lagrangian:

$$\frac{\partial}{\partial t} \mathcal{E} \equiv \frac{\partial}{\partial t} \left( \sum_{\text{sp}} \int dV dW f H + \int dV \frac{B_{\perp}^2}{8\pi} \right) = 0$$

Note: the EM total energy is conserved only across-species.

## Global energy conservation, electrostatic case

$$\frac{\partial}{\partial t} \mathcal{E} = \frac{\partial}{\partial t} \left( \sum_{\text{sp}} \int dV dW f H \right) = 0$$

$$\frac{\partial}{\partial t} \left( \sum_{\text{sp}} \int dV dW f \left( m \frac{U^2}{2} + \mu B + e J_0 \Phi \right) \right) \equiv \dot{\mathcal{E}}_k + \dot{\mathcal{E}}_F = 0$$

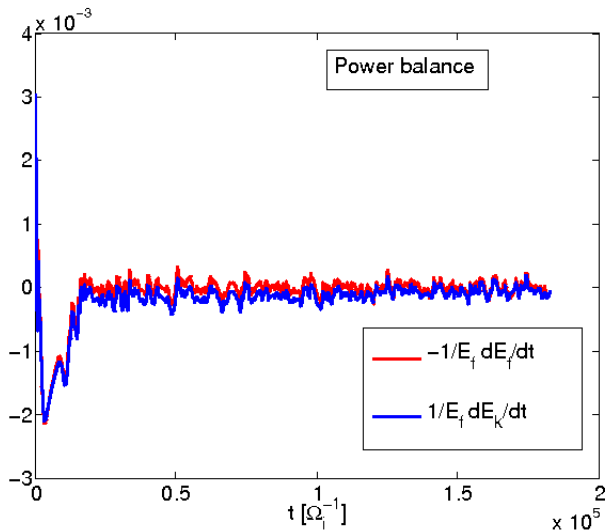
- It can be easily verified, using the Euler-Lagrange equations, that

$$\dot{\mathcal{E}}_k = - \sum_{\text{sp}} \int dV dW f e \nabla(J_0 \Phi) \cdot \dot{\mathbf{R}}_0$$

- Power balance equation:

$$\frac{1}{2\mathcal{E}_F} \dot{\mathcal{E}}_F = - \frac{1}{2\mathcal{E}_F} \sum_{\text{sp}} \int dV dW f e \nabla(J_0 \Phi) \cdot \dot{\mathbf{R}}_0$$

## Power balance equation in CYCLONE, nonlinear PIC



- CYCLONE base case: DIII-D (circular) equilibrium.



## Power balance is a powerful tool

- The power balance equation not only gives an indication of the quality of the simulation, but also provides, in **linear** simulations, a measure of the instantaneous **growth rate**:

$$\mathcal{E}_F(\mathbf{R}, t) = \bar{\mathcal{E}}_F(\mathbf{R}) \exp(2\gamma t)$$

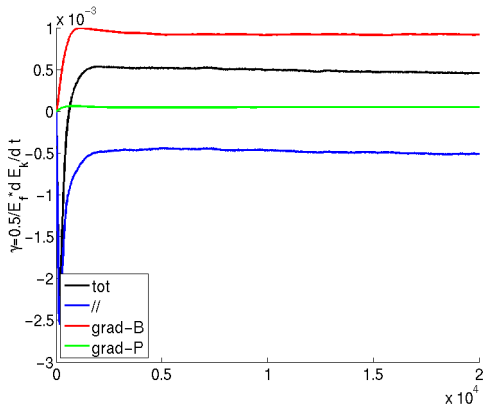
$$\gamma = \frac{1}{2\mathcal{E}_F} \sum_{sp} \int dV dW f e \nabla(J_0 \Phi) \cdot \dot{\mathbf{R}}_0$$

$$\dot{\mathbf{R}}_0 = \frac{p_{\parallel}}{m} \mathbf{b} - \left(\frac{p_{\parallel}}{m}\right)^2 \frac{mc}{eB_{\parallel}^*} \mathbf{b} \times \frac{\nabla p}{B^2} + \left(\frac{\mu B}{m} + \left(\frac{p_{\parallel}}{m}\right)^2\right) \frac{mc}{eB_{\parallel}^*} \mathbf{b} \times \frac{\nabla B}{B}$$

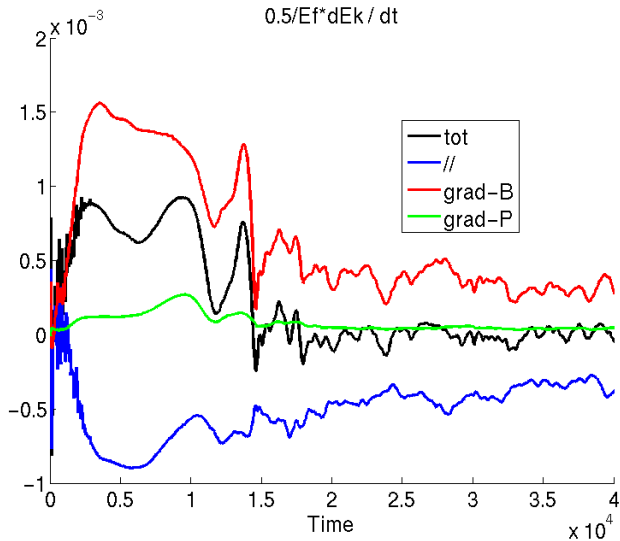
$$\gamma = \frac{1}{2\mathcal{E}_F} \sum_{sp} \int dV dW f e \nabla(J_0 \Phi) \cdot (\mathbf{v}_{\parallel} + \mathbf{v}_{\nabla p} + \mathbf{v}_{\nabla B})$$

# Instantaneous growth rate for ITG modes, linear

$$\gamma = \frac{1}{2\mathcal{E}_F} \sum_{\text{sp}} \int dV dW f e \nabla(J_0 \Phi) \cdot (\mathbf{v}_{\parallel} + \mathbf{v}_{\nabla p} + \mathbf{v}_{\nabla B})$$



# Instantaneous growth rate for ITG modes, nonlinear



## Summary: electrostatic, linear polarization GK equations

$$\frac{\partial f}{\partial t} + \dot{\mathbf{R}} \cdot \nabla f + \dot{p}_{\parallel} \frac{\partial f}{\partial p_{\parallel}} = 0$$

$$\dot{\mathbf{R}} = \frac{p_{\parallel} \mathbf{B}^*}{m B_{\parallel}^*} - \frac{c}{e B B_{\parallel}^*} \mathbf{F} \cdot [\mu \nabla B + e \nabla J_0 \Phi]$$

$$\dot{p}_{\parallel} = -\frac{\mathbf{B}^*}{B_{\parallel}^*} \cdot [\mu \nabla B + e \nabla J_0 \Phi]$$

$$\sum_{\text{sp}} \left( \int dW e J_0 f + \nabla \cdot \left( \frac{n_0 m c^2}{B^2} \nabla_{\perp} \Phi \right) \right) = 0$$

- **Energetic consistency**: the same Hamiltonian must be used to construct the polarization equation and the gyrokinetic Vlasov equations.
- This also implies that the approximations made cannot be relaxed once the equations have been derived.

## Energetic consistency can be easily broken

$$\frac{\partial f}{\partial t} + \dot{\mathbf{R}} \cdot \nabla f + \dot{p}_{\parallel} \frac{\partial f}{\partial p_{\parallel}} = 0$$

$$\dot{\mathbf{R}} = \frac{p_{\parallel} \mathbf{B}^*}{m B_{\parallel}^*} - \frac{c}{e B B_{\parallel}^*} \mathbf{F} \cdot [\mu \nabla B + e \nabla J_0 \Phi]$$

$$\dot{p}_{\parallel} = -\frac{\mathbf{B}^*}{B_{\parallel}^*} \cdot [\mu \nabla B + e \nabla J_0 \Phi]$$

$$\sum_{\text{sp}} \left( \int dW e J_0 f + \nabla \cdot \left( \frac{n(t) m c^2}{B^2} \nabla_{\perp} \Phi \right) \right) = 0$$

**Energetic consistency is broken:**

- nonlinear polarization implies using  $(H_0 + H_1 + H_2)f$  in the Lagrangian for field equations;  
→ second order terms must be included in the Euler-Lagrange equations.

## Energetic consistency can be easily broken

$$\frac{\partial f}{\partial t} + \dot{\mathbf{R}} \cdot \nabla f + \dot{p}_{\parallel} \frac{\partial f}{\partial p_{\parallel}} = 0$$

$$\dot{\mathbf{R}} = \frac{\rho_{\parallel} \mathbf{B}^*}{m B_{\parallel}^*} - \frac{c}{e B B_{\parallel}^*} \mathbf{F} \cdot [\mu \nabla B + e \nabla J_0 \Phi] + O(\Phi^2)$$

$$\dot{p}_{\parallel} = -\frac{\mathbf{B}^*}{B_{\parallel}^*} \cdot [\mu \nabla B + e \nabla J_0 \Phi] + O(\Phi^2)$$

$$\sum_{\text{sp}} \left( \int dW e J_0 f + \nabla \cdot \left( \frac{n(t) m c^2}{B^2} \nabla_{\perp} \Phi \right) \right) = 0$$

Energetic consistency is restored:

- nonlinear polarization implies using  $(H_0 + H_1 + H_2)f$  in the Lagrangian for field equations;  
→ second order terms must be included in the Euler-Lagrange equations.

## PIC discretization

- $f$  is approximated by a sum of  $N$  markers, each defined by a position in phase-space  $(\mathbf{R}(t), p_{\parallel}(t), \mu)$  and a weight  $w$ .

$$f \simeq f_N(\mathbf{R}(t), p_{\parallel}(t), \mu) = \sum_{k=1}^N w_k \delta(\mathbf{R} - \mathbf{R}_k(t)) \delta(p_{\parallel} - p_{\parallel k}(t)) \delta(\mu - \mu_k)$$

- The weights  $w_k$  are time independent (replace  $f$  in Vlasov eq...).
- The weights are distributed accordingly to a certain probability density function  $g$  (importance sampling).

## Euler-Lagrange equations, time evolution

- The time evolution is done by advancing the markers along the characteristics of the Vlasov equation:

$$\begin{aligned}\dot{\mathbf{R}}_k &= \left( \frac{p_{\parallel k} \mathbf{B}^*}{m B_{\parallel}^*} - \frac{c}{e B B_{\parallel}^*} \mathbf{F} \cdot [\mu_k \nabla B + e \nabla J_0 \Phi] \right)_k \\ p_{\parallel k} \dot{} &= \left( -\frac{\mathbf{B}^*}{B_{\parallel}^*} \cdot [\mu_k \nabla B + e \nabla J_0 \Phi] \right)_k\end{aligned}$$

given an initial condition  $\mathbf{R}_k(0) = \mathbf{R}_k^0$ ,  $\mu_k, p_{\parallel k}(0) = p_{\parallel k}^0$ .

- $J_0 \Phi$  at the marker position is needed.
- $\Phi$  is computed by solving the polarisation equation on a grid of physical space, after having constructed the charge density  $\rho_N = \int dW e J_0 f$  on the grid.



The gyroaverage operator  $J_0$  has the form of Bessel- $J_0$

$$\begin{aligned} J_0 \Phi &= \frac{1}{2\pi} \int_0^{2\pi} \Phi(\mathbf{R} + \vec{\rho}_i) d\theta = \\ &= \frac{1}{2\pi} \int_0^{2\pi} \left( \int \frac{1}{(2\pi)^3} \hat{\Phi}(\mathbf{k}) e^{i\mathbf{k} \cdot (\mathbf{R} + \vec{\rho}_i)} d\mathbf{k} \right) d\theta = \\ &= \int \frac{1}{(2\pi)^3} \hat{\Phi}(\mathbf{k}) \left( \frac{1}{2\pi} \int_0^{2\pi} e^{ik_{\perp} \rho_i \cos(\theta)} d\theta \right) e^{i\mathbf{k} \cdot \mathbf{R}} d\mathbf{k} = \\ &= \frac{1}{(2\pi)^3} \int \hat{\Phi}(\mathbf{k}) J_0(k_{\perp} \rho_i) e^{i\mathbf{k} \cdot \mathbf{R}} d\mathbf{k} \quad , \end{aligned}$$

$\hat{\Phi}$  Fourier transformed  $\Phi$ ,  $\rho_i = \frac{k_B T m c^2}{e^2 B^2}$ .

- $J_0$  has the form, in Fourier space, of a multiplication of Fourier coefficients by the zeroth Bessel functions  $J_0(k_{\perp} \rho_i)$ .

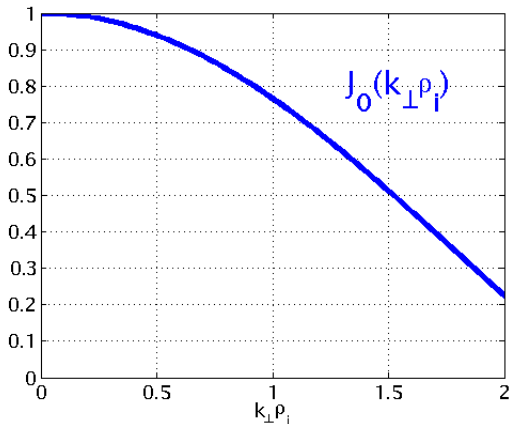
## The gyroaveraged electrostatic potential $J_0\Phi$

$$\begin{aligned} J_0\Phi &= \frac{1}{2\pi} \int_0^{2\pi} \Phi(\mathbf{R} + \vec{\rho}_i) d\theta = \\ &= \frac{1}{2\pi} \int_0^{2\pi} \left( \int \frac{1}{(2\pi)^3} \hat{\Phi}(\mathbf{k}) e^{i\mathbf{k}\cdot(\mathbf{R}+\vec{\rho}_i)} d\mathbf{k} \right) d\theta = \\ &= \int \frac{1}{(2\pi)^3} \hat{\Phi}(\mathbf{k}) \left( \frac{1}{2\pi} \int_0^{2\pi} e^{ik_{\perp}\rho_i \cos(\theta)} d\theta \right) e^{i\mathbf{k}\cdot\mathbf{R}} d\mathbf{k} = \\ &= \frac{1}{(2\pi)^3} \int \hat{\Phi}(\mathbf{k}) J_0(k_{\perp}\rho_i) e^{i\mathbf{k}\cdot\mathbf{R}} d\mathbf{k} , \end{aligned}$$

$\hat{\Phi}$  Fourier transformed  $\Phi$ ,  $\rho_i = \frac{k_B T m c^2}{e^2 B^2}$ .

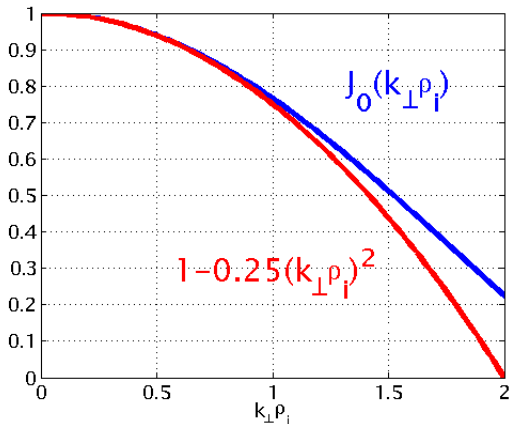
- $J_0$  has the form, in Fourier space, of a multiplication of Fourier coefficients by the zeroth Bessel functions  $J_0(k_{\perp}\rho_i)$ .

## Bessel $J_0$ smooths out small variations



- $J_0$  acts as a smoothing operator on  $\Phi$ .

## Bessel $J_0$ smooths out small variations



- $J_0$  acts as a smoothing operator on  $\Phi$ .

## A discretized gyroaverage operator

- Direct calculation of  $J_0\Phi$  for each individual marker has to account for its interaction with all the waves in the system, computationally prohibitive.
- Alternatively, the gyroaverage procedure can be approximated by an average over a number of points on the gyro-ring [Lee 1987].

$$J_0\Phi = \frac{1}{2\pi} \int_0^{2\pi} \Phi(\mathbf{R} + \vec{\rho}) d\theta \simeq \frac{1}{N_{avg}} \sum_{i=1}^{N_{avg}} \Phi(\mathbf{x}_i)$$

When four quadrature points are used, this procedure is equivalent to replace  $J_0$  with a Taylor expansion  $J_0(k_{\perp}\rho_i) \simeq 1 - \frac{1}{4}(k_{\perp}\rho_i)^2$  and to compute the transverse Laplacian using second order finite differences.

## Simple proof

- Consider an equispaced 2D grid, with grid spacing  $h = \rho_i$  in both directions.
- Each point of the grid is defined by a pair of indexes  $(i, j)$ :

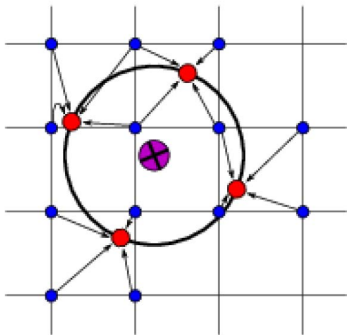
$$J_0(\mathbf{R}) \simeq \Phi - \frac{1}{4}\rho_i^2 \nabla_{\perp}^2 \Phi(\mathbf{R})$$

$$\begin{aligned} J_0\Phi_{i,j} &\simeq \Phi_{ij} + \frac{\rho_i^2}{4h^2}(\Phi_{i+1,j} + \Phi_{i-1,j} - 2\Phi_{i,j} + \Phi_{i,j+1} + \Phi_{i,j-1} - 2\Phi_{i,j}) \\ &= \frac{1}{4}(\Phi_{i+1,j} + \Phi_{i-1,j} + \Phi_{i,j+1} + \Phi_{i,j-1}) \end{aligned}$$

where the standard second order centred finite difference scheme  $\nabla^2\Phi_j = (-\Phi_{j+1} + 2\Phi_j - \Phi_{j-1})/h^2$  was used in both directions.

## Example: 4-point average in 2D, linear interpolation

$$J_0\Phi = \frac{1}{2\pi} \int_0^{2\pi} \Phi(\mathbf{R} + \rho) d\theta \simeq \frac{1}{4} \sum_{i=1}^4 \Phi(\mathbf{x}_i)$$



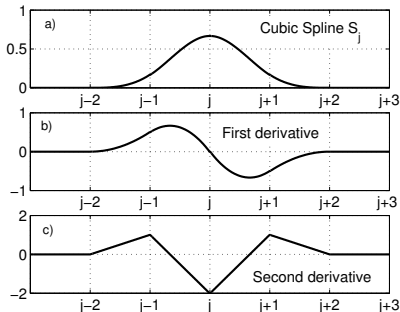
- $\Phi$  is defined on a grid (blue dots).
- interpolation to get  $\Phi$  on some points ( $\mathbf{x}_i$ ) on the ring (red dots).
- Average to get  $J_0\Phi$  at the tracer position.

## Polarization (Poisson) equation, B-splines

The polarisation equation is solved using finite elements:

$$\Phi(\mathbf{x}, t) = \sum_{\mu} \Phi_{\mu}(t) \Lambda_{\mu}(\mathbf{x})$$

Where  $\Phi_{\mu}(t)$  are real numbers, and  $\Lambda_{\mu}(\mathbf{x}) = \Lambda_j(x_1)\Lambda_k(x_2)\Lambda_l(x_3)$  is a 3D product of polynomial basis functions (cubic B-splines).





## Polarization (Poisson) equation, B-splines

- The polarization equation becomes:

$$\sum_{sp} \sum_{\mu} \Phi_{\mu} \left( -\nabla_{\perp} \cdot \frac{n_0 mc^2}{b^2} \nabla_{\perp} \Lambda_{\mu}(\mathbf{x}) \right) = \sum_{sp} \int dW e J_0 f$$

- Galerkin method:

- a) Multiply the equation by another test function  $g(\mathbf{x}) = \Lambda_{\nu}(\mathbf{x})$ .
- b) Integrate the resulting equation over configuration space.

$$-\sum_{\mu} \Phi_{\mu} \int dV \sum_{sp} \Lambda_{\nu}(\mathbf{x}) \nabla_{\perp} \cdot \frac{n_0 mc^2}{B^2} \nabla_{\perp} \Lambda_{\mu}(\mathbf{x}) = \sum_{sp} \int dW dV e J_0 f \Lambda_{\nu}(\mathbf{x})$$

having integrated the left hand side by parts.

- This equation is usually called the discretized weak form of the polarization equation.

## Discretized polarization equation, set of linear equations

- The right hand side is now rewritten using the PIC approximation for  $J_0 f$  and by integrating the delta functions:

$$-\sum_{\mu} \Phi_{\mu} \sum_{\text{sp}} \int d\mathbf{R} \Lambda_{\nu}(\mathbf{R}) \nabla_{\perp} \cdot \frac{n_0 m c^2}{B^2} \nabla_{\perp} \Lambda_{\mu}(\mathbf{R}) = \sum_{\text{sp}} \left( e \sum_{k=1}^N w_k \frac{1}{N_{gr,k}} \sum_{\beta=1}^{N_{gr,k}} \Lambda_{\nu}(\mathbf{x}_{k,\beta}) \right)$$

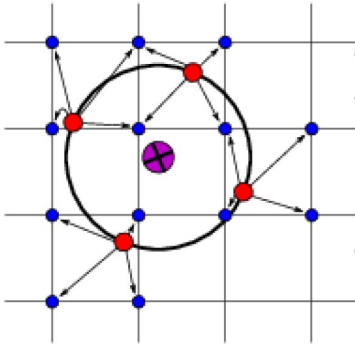
- The previous equation is actually a set of linear equations:

$$\sum_{\mu} A_{\mu\nu} \Phi_{\mu} = b_{\nu}$$

- $A_{\mu\nu}$  is a sparse, symmetric and positive definite matrix

## Charge assignment, linear B-splines

$$\sum_{sp} \left( e \sum_{k=1}^N \frac{1}{N_{gr,k}} \sum_{\beta=1}^{N_{gr,k}} w_k \Lambda_{\nu}(\mathbf{x}_{k,\beta}) \right)$$



- Scatter operation
- each sample point (red dots) contributes to the charge of 4 grid points (blue dots).
- for 3D cubic B-Splines, 64 grid points.

# Skeleton of a finite element PIC code

## Initialization:

- Construct the matrix:

$$A_{\mu\nu} = - \sum_{\mu} \Phi_{\mu} \sum_{\text{sp}} \int d\mathbf{R} \Lambda_{\nu}(\mathbf{R}) \nabla_{\perp} \cdot \frac{n_0 m c^2}{B^2} \nabla_{\perp} \Lambda_{\mu}(\mathbf{R})$$

- Initialize marker positions and weights:

$$\mathbf{R}_{\mathbf{k}}(0) = \mathbf{R}_{\mathbf{k}}^0, \quad \mu_{\mathbf{k}}, \quad p_{\parallel \mathbf{k}}(0) = p_{\parallel \mathbf{k}}^0, \quad w_{\mathbf{k}}$$

## Skeleton of a finite element PIC code

### Main loop:

- Charge assignment:

$$b_\nu = \sum_{\text{sp}} \left( e \sum_{k=1}^N w_k \frac{1}{N_{gr,k}} \sum_{\beta=1}^{N_{gr,k}} \Lambda_\nu(\mathbf{x}_{k,\beta}) \right)$$

- Solve  $\sum_\mu A_{\mu\nu} \Phi_\mu = b_\nu$  to get:

$$\Phi(\mathbf{x}, t) = \sum_{\mu} \Phi_\mu(t) \Lambda_\mu(\mathbf{x})$$

- Calculate  $J_0 \Phi$  at each marker position.
- Update marker position using Euler-Lagrange (ODEs):

$$\dot{\mathbf{R}}_k = \left( \frac{p_{\parallel k} \mathbf{B}^*}{m B_{\parallel}^*} - \frac{c}{e B B_{\parallel}^*} \mathbf{F} \cdot [\mu_k \nabla B + e \nabla J_0 \Phi] \right)_k$$
$$p_{\parallel k} \dot{=} \left( -\frac{\mathbf{B}^*}{B_{\parallel}^*} \cdot [\mu_k \nabla B + e \nabla J_0 \Phi] \right)_k$$

## Control variate PIC ( $\delta f$ method)

$$f(\mathbf{R}, v_{\parallel}, \mu, t) = f_0(\psi_0, \epsilon, \mu, t) + \delta f(\mathbf{R}, v_{\parallel}, \mu, t)$$

- Particle kinetic energy  $\epsilon = m_i (\mu B + U^2/2)$ , the magnetic momentum  $\mu$  and the toroidal canonical momentum  $\psi_0 = \psi + (m_i/q_i)Rv_{\varphi}$  are constant of motion on the unperturbed trajectories ( $\Phi = 0$ ).

→  $f_0$  is a stationary solution of the Vlasov equation with  $\Phi = 0$ .

- The PIC approximation of  $f$  is now:

$$\begin{aligned} f &\simeq f_0 + \delta f_N(\mathbf{R}(t), p_{\parallel}(t), \mu) \\ &= f_0 + \sum_{k=1}^N w_k \delta(\mathbf{R} - \mathbf{R}_k(t)) \delta(p_{\parallel} - p_{\parallel k}(t)) \delta(\mu - \mu_k) \end{aligned}$$

## Control variate PIC ( $\delta f$ method)

- The Vlasov equation becomes a time evolution equation for  $\delta f$ :

$$\frac{d}{dt}f = \frac{d}{dt}\delta f + \frac{d}{dt}f_0 = 0$$

$$\frac{d}{dt}\delta f = -\frac{d}{dt}f_0 \equiv \tau(J_0\Phi)$$

and consequently for the weights:

$$\dot{w}_k = \tau(J_0\Phi)|_k$$

## Skeleton of a finite element PIC code

### Main loop:

- Charge assignment:

$$b_\nu = \sum_{\text{sp}} \left( e \sum_{k=1}^N w_k \frac{1}{N_{gr,k}} \sum_{\beta=1}^{N_{gr,k}} \Lambda_\nu(\mathbf{x}_{k,\beta}) \right)$$

- Solve  $\sum_\mu A_{\mu\nu} \Phi_\mu = b_\nu$  to get:

$$\Phi(\mathbf{x}, t) = \sum_\mu \Phi_\mu(t) \Lambda_\mu(\mathbf{x})$$

- Calculate  $J_0 \Phi$  at each marker position.
- Update marker position using Euler-Lagrange (ODEs):

$$\begin{aligned} \dot{\mathbf{R}}_k &= \dots \\ p_{||k}^{\dot{}} &= \dots \\ \dot{w}_k &= \tau(J_0 \Phi)|_k \end{aligned}$$



## Simple Monte-Carlo estimate for the noise

- Statistical noise (Aydemir 1994):

Error  $\epsilon$  introduced when the moment of the distribution function (density) is evaluated with a **finite number  $N$  of particles**,  $\epsilon \simeq \sigma/\sqrt{N}$

$$\rho_{noise}^2 \simeq \frac{N_G}{N} \langle w^2 \rangle G ; \quad \langle w^2 \rangle \equiv \frac{1}{N} \sum_{i=1}^N w_i^2$$

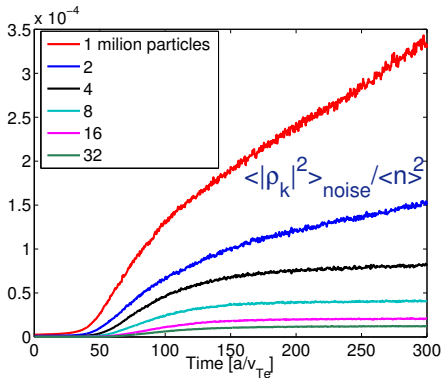
$N_G$ , number of Fourier modes included in the simulation.  
 $G$  accounts for FLR filtering and grid projection filtering.

- Noise can be reduced by:
  1. **Increasing** the number of tracers  $N$ .
  2. **Reducing** the number of modes  $N_G \rightarrow$  Fourier filtering.
  3. **Reducing**  $\langle w^2 \rangle$  (MC, reducing  $\sigma$ )
  4. **Carefully choosing** the projection algorithm, i.e.  $G$ .

## The statistical appears in the charge assignment

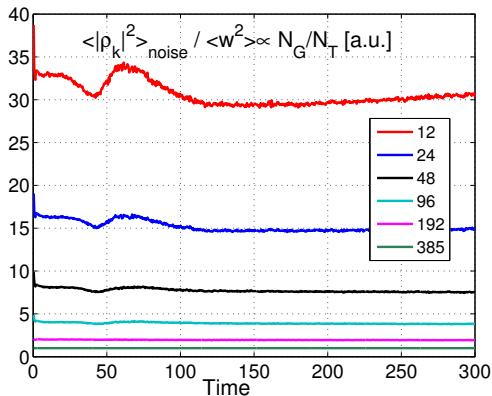
- In certain codes, the level of noise can be measured during the charge assignment:

Direct measure of  $|\rho|_{noise}^2$  by evaluating the average value of  $|\rho_k|^2$  for the non-resonant (filtered) modes.



Level of noise,  $\rho_e^* = 1/80$

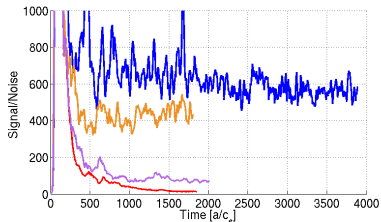
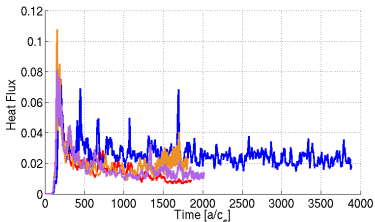
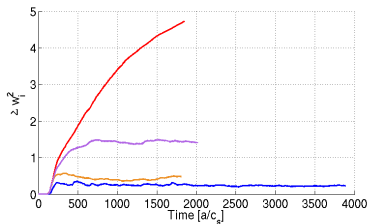
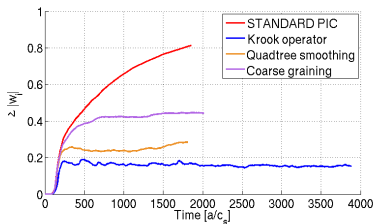
## MC estimate validation: noise scaling with $N/N_G$



The scaling of the turbulence in number of particles per mode  $N_G/N$  is satisfied

$$\frac{\rho_{noise}^2}{\langle w^2 \rangle} \simeq \frac{N_G}{N} G$$

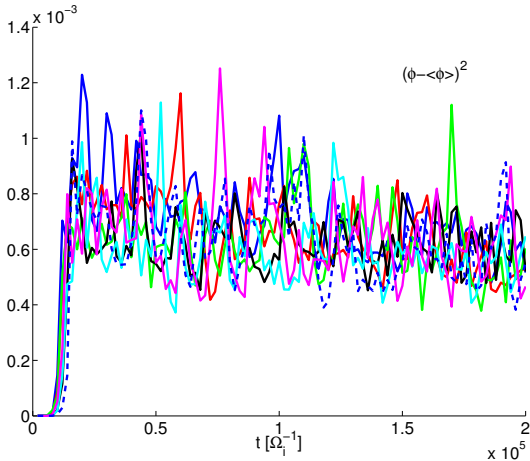
# Variance reduction techniques (Monte-Carlo)



- Very long simulations; Different heat sources → different fluxes.

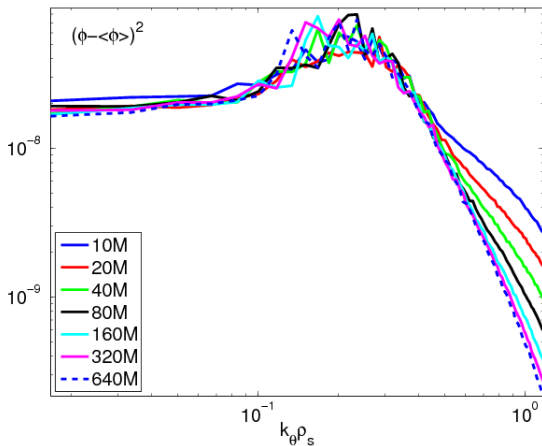
## Convergence in number of markers N

- Radial averaged heat fluxes or electrostatic potentials are very robust... not a good choice.



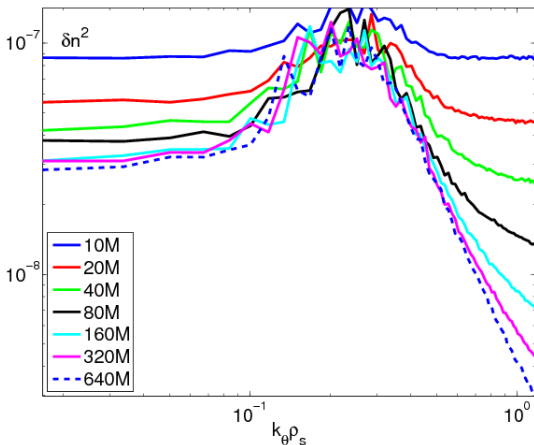
# Spectra give good insights on the quality of the simulation

- Time averaged spectrum: nonzonal electrostatic potential



# Density fluctuation spectrum, slow converge in N

- Time averaged spectrum: density fluctuation



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